



令

$$\mathbf{g}(\mathbf{x}) = (g_1(\mathbf{x}), g_2(\mathbf{x}), \dots, g_m(\mathbf{x}))^T$$
 其中  $\mathbf{x} = (x_1, x_2, \dots, x_{n-m})$  将上述  $n-m$  个等式写成向量形式，有
 
$$\left( \frac{\partial f(\mathbf{x}_0)}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x}_0)}{\partial x_{n-m}} \right) + \left( \frac{\partial f(\mathbf{x}_0)}{\partial x_{n-m+1}}, \dots, \frac{\partial f(\mathbf{x}_0)}{\partial x_n} \right) \mathbf{g}(\mathbf{x}_0) = 0$$
 由于  $\mathbf{g}(\mathbf{x}_0) = -\left( \begin{array}{c} \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_{n-m+1}} & \dots & \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_{n-m+2}} & \dots & \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_n} \\ \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m+1}} & \dots & \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m+2}} & \dots & \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_n} \\ \dots & \dots & \dots & \dots & \dots \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m+1}} & \dots & \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m+2}} & \dots & \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_n} \end{array} \right)^{-1} \left( \begin{array}{c} \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_1} & \dots & \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_{n-m}} \\ \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_1} & \dots & \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m}} \\ \dots & \dots & \dots \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_1} & \dots & \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m}} \end{array} \right) \triangleq -A^{-1}B$ 
 注意到  $-\left( \frac{\partial f(\mathbf{x}_0)}{\partial x_{n-m+1}}, \dots, \frac{\partial f(\mathbf{x}_0)}{\partial x_n} \right) \cdot A^{-1}$  是一个  $m$  维行向量，我们可以将其记为  $-\left( \frac{\partial f(\mathbf{x}_0)}{\partial x_{n-m+1}}, \dots, \frac{\partial f(\mathbf{x}_0)}{\partial x_n} \right) \cdot A^{-1} = \left( \lambda_1, \lambda_2, \dots, \lambda_m \right)$  将  $\left( \frac{\partial f(\mathbf{x}_0)}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x}_0)}{\partial x_{n-m}} \right) + \left( \lambda_1, \lambda_2, \dots, \lambda_m \right) \left( \begin{array}{c} \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_1} & \dots & \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_{n-m}} \\ \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_1} & \dots & \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m}} \\ \dots & \dots & \dots \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_1} & \dots & \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m}} \end{array} \right) = 0$  另外我们可以将  $\left( \frac{\partial f(\mathbf{x}_0)}{\partial x_{n-m+1}}, \dots, \frac{\partial f(\mathbf{x}_0)}{\partial x_n} \right) + \left( \lambda_1, \lambda_2, \dots, \lambda_m \right) \left( \begin{array}{c} \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_{n-m+1}} & \dots & \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_{n-m+2}} & \dots & \frac{\partial \varphi_1(\mathbf{x}_0)}{\partial x_n} \\ \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m+1}} & \dots & \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m+2}} & \dots & \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_n} \\ \dots & \dots & \dots & \dots & \dots \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m+1}} & \dots & \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m+2}} & \dots & \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_n} \end{array} \right)$

$$\begin{matrix} \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_{n-m+2}} & \cdots & \\ \frac{\partial \varphi_2(\mathbf{x}_0)}{\partial x_n} & \vdots & \ddots & \vdots \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m+1}} & & & \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_{n-m+2}} & \cdots & & \\ \frac{\partial \varphi_m(\mathbf{x}_0)}{\partial x_n} \end{matrix} \end{matrix} = 0$$
 将  $(\mathbf{x}_0, \lambda)$  写成分量形式再加上约束条件即可证明。

## 拉格朗日乘子法

构造函数  $F(x_1, \dots, x_n, \lambda_1, \dots, \lambda_m) = f(\mathbf{x}) + \sum_{j=1}^m \lambda_j \varphi_j(\mathbf{x})$  则上述求条件极值点的必要条件形式转化为  $F$  的通常极值的必要条件

$$\begin{cases} \frac{\partial F(\mathbf{x}_0)}{\partial x_i} = 0 & (i=1, 2, \dots, n) \\ \frac{\partial F(\mathbf{x}_0)}{\partial \lambda_j} = 0 & (j=1, 2, \dots, m) \end{cases}$$

此即拉格朗日乘子法

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